### Application of Ensemble Kalman Filter for satellite altimetry data assimilation in the Mediterranean Sea

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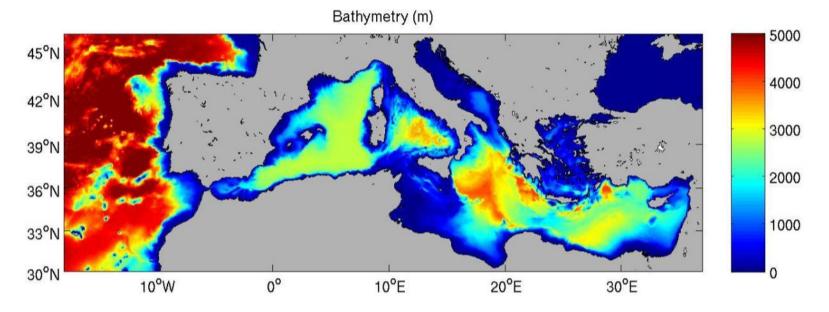


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# Objectives

- Test sbPOM + ENKF for application in the Mediterranean Sea using controlled experiments.
- Implement coastal ocean forecasting in the western Mediterranean Sea using real-time HF radar, glider, and satellite observations.

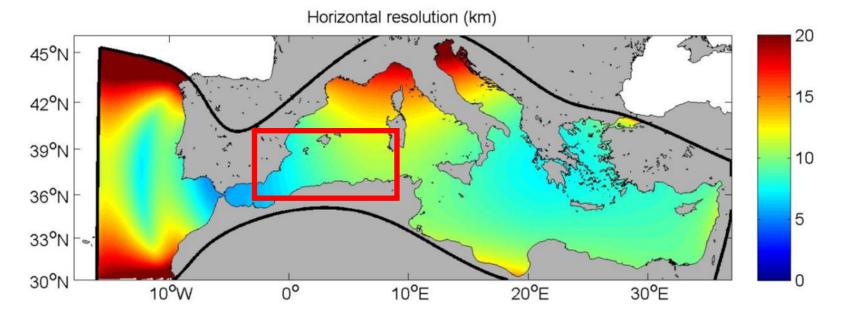


# True ocean: POP model

- High-resolution (1/16°) parallel ocean program (POP) in the Mediterranean with 72 non-uniform vertical levels.
  (Jordi and Wang, 2009, Ocean Modeling).
- A 12-year simulation forced by a perpetual high-resolution atmospheric forcing corresponding to year 1987.
- Observations of SSH are generated from the last January of the simulation on the 1/8° regular grid where satellite altimetry data is provided at daily interval.

# Assimilation: sbPOM +ENKF

- Implementation of the sbPOM model in the Mediterranean Sea with variable horizontal resolution (674 x 226 grid points) and 31 non-uniform sigma levels. The resolution is ~3 km in the Strait of Gibraltar.
- The simulations run for 30 days. Assimilation steps are daily.
- 32 ensemble members generated by independent initializations and wind fields.



# Generation of ensembles

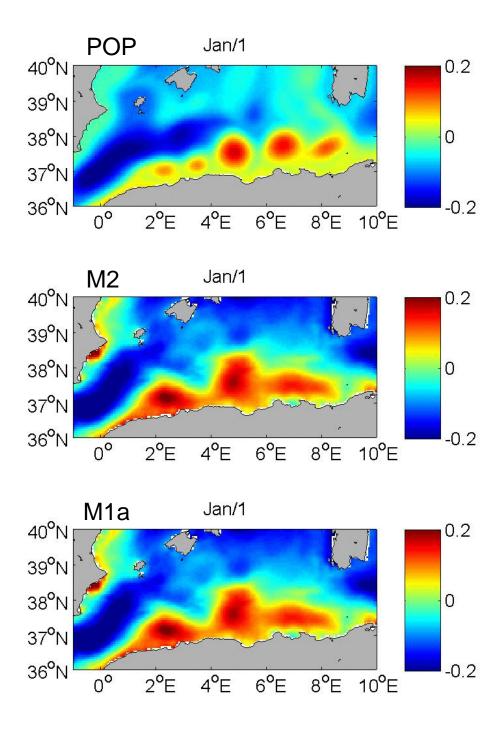
- 8 initial model states are generated by sampling the POP model every January 1<sup>st</sup> for the last 8 years of simulation. This method ensures that initial ensembles are representative of the full real (POP) phase space.
- 32 wind fields are generated by decomposing the real wind as sums of EOFs. The weights of the decomposition are multiplied by a random coefficient in the range 1 ± 0.4. The perturbed wind fields are obtained by summing back the weighted EOFs.

# Assimilation experiments

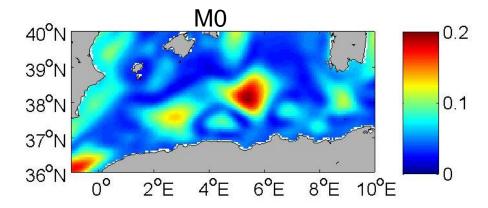
- M0: a free run of the ensemble members (no assimilation) is performed to compare the relative gain of the ENKF.
- M1: assimilation with a reduced model state:
  - M1a: the subsurface temperature and salinity are projected (T, S).
  - M1b: the subsurface currents are projected (u, v).
- M2: assimilation with full model states (SSH, transport, u, v, T, S).

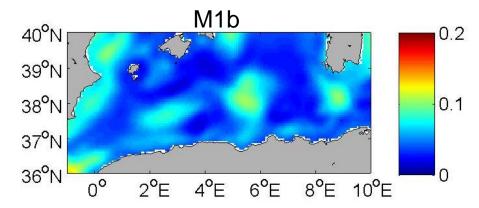
## Results -

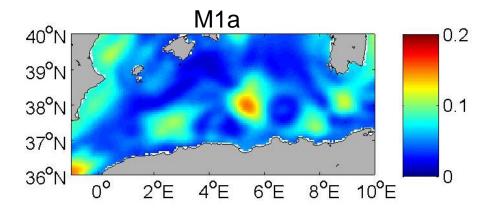
Animations of SSH (m) from real ocean (POP) and ensembles averages.

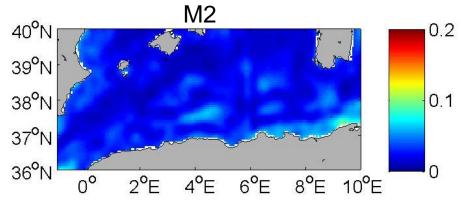


### Results - RMS error of SSH (m)

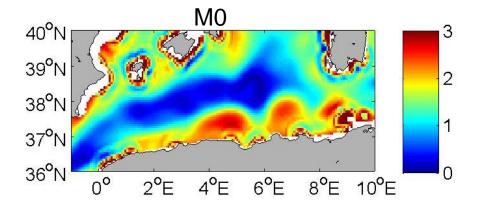


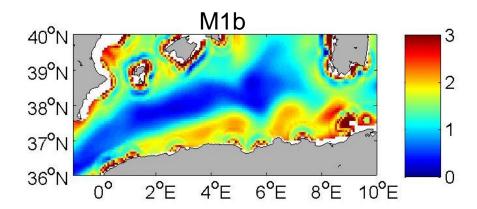


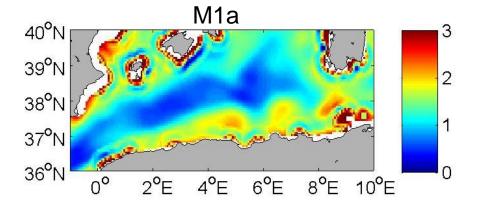


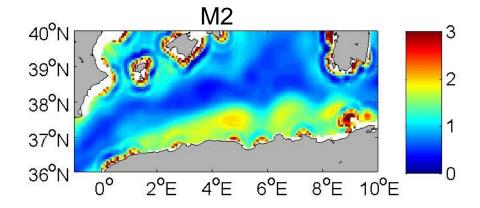


#### Results - RMS error of T (°C) at 100 m depth

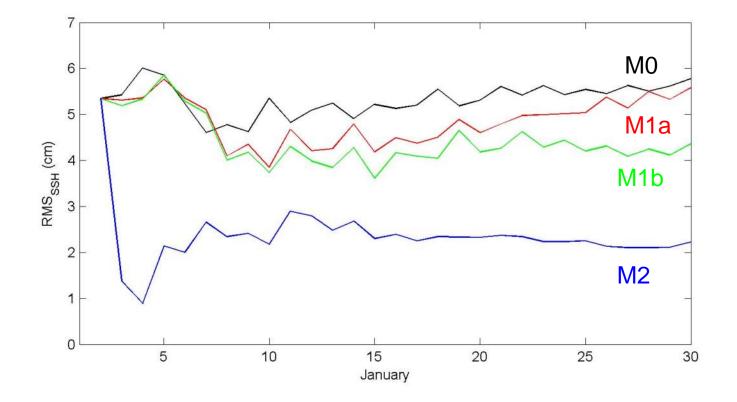








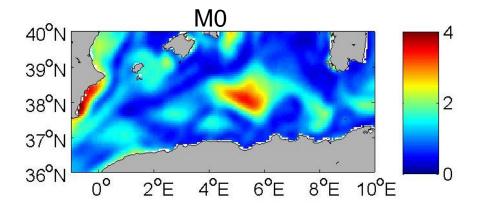
### Results - RMS of SSH (cm) averaged in the Algerian basin

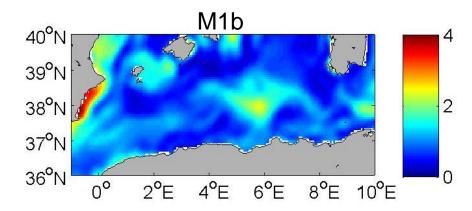


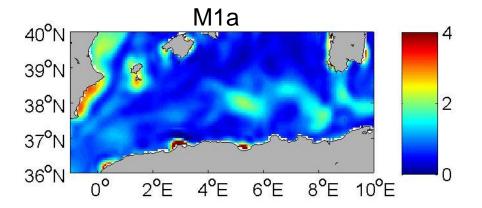
# Conclusion

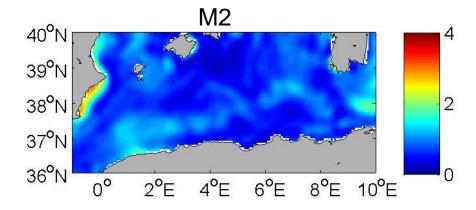
- An advanced assimilation method (ENKF) is coupled to sbPOM. The sbPOM + ENKF works on parallel architectures (1028 = 32 × 32).
- The sbPOM + ENKF is able to reproduce the mesoscale activity of the Mediterranean Sea (Algerian basin) using synthetic observations of SSH from another ocean model (POP).
- A sbPOM + ENKF test case will be made available at the sbPOM web page.

### Results - RMS of SST (°C) averaged in time

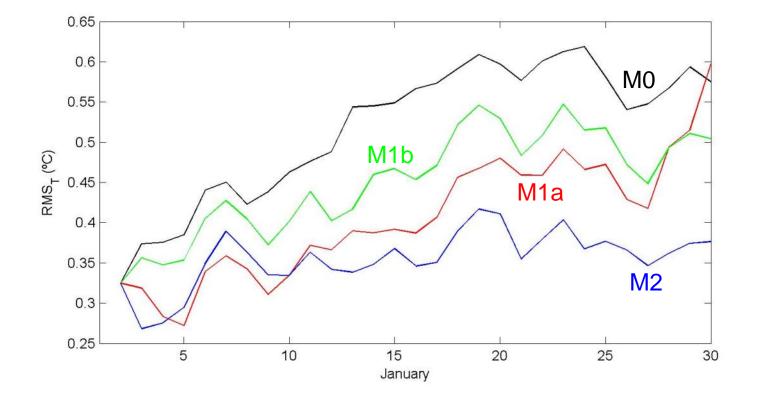








### Results - RMS of SST (°C) averaged in Algerian basin



# sbPOM + ENKF

#### A parallel ENKF algorithm is coupled to the sbPOM. Modifications to sbPOM are minimal.

▼	i enkf	ENKF code:
	assimilation_tools.f	Main assimilation (ENKF) subroutines
	ensemble_tools.f	Computations involving the ensemble members
	io_tools.F	Parallel I/O for the ensemble members
	model_tools.f	Communication with the model (sbPOM)
	mpi_tools.f	Parallel tasks (communication between processors)
⊳	🧰 in	Input files
⊳	i obs	Observations files
⊳	🧰 out	Output files (ensembles averages and variances)
⊳	pom	Original sbPOM code (with minimal modifications)
⊳	prep	Matlab scripts to generate input files
⊳	proc	Matlab scripts to process output files
	📓 enkf.h	ENKF dimensions (ensemble size, # model states, # observations)
	enkf.nml	Input control file for ENKF
	enkf.sh	Script to run the code
	main.f	Main driver
	makefile	Make file (compile the code)
	📓 pom.h	Global and local dimensions for sbPOM model
	pom.nml	Input control file for sbPOM